

	Type	L #	Hits	Search Text	DBs
1	IS&R	L1	2551	((335/78,229-234) or (200/181)).CCLS.	US- PGPUB; USPAT; EPO; JPO; DERWEN T; IBM_TD B
2	BRS	L2	1817	spine same (motor actuator)	US- PGPUB; USPAT; EPO; JPO; DERWEN T; IBM_TD B
3	BRS	L3	112	spine same (motor actuator) and robot\$	US- PGPUB; USPAT; EPO; JPO; DERWEN T; IBM_TD B
4	BRS	L4	344340	(electrostatic\$ electro- static\$ "electro static")	US- PGPUB; USPAT; EPO; JPO; DERWEN T; IBM_TD B

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5	BRS	L5	10785	L4 and electrode and (beam cantilever) and (controller oscilatore generator pwm)	US- PGPUB; USPAT; EPO; JPO; DERWEN T; IBM_TD B
6	BRS	L6	2447	spine.clm.	US- PGPUB
7	BRS	L7	10469	(electrostatic\$ electro-static\$ "electro static").clm.	US- PGPUB
8	BRS	L8	82463	(motor actuator solenoid).clm.	US- PGPUB
9	BRS	L9	390	8 near3 7	US- PGPUB
10	BRS	L10	1	9 and 6	US- PGPUB
11	BRS	L11	95250	plate.clm.	US- PGPUB
12	BRS	L12	90	9 and 11	US- PGPUB
13	BRS	L14	57042	flex\$4.clm.	US- PGPUB
14	BRS	L15	92	9 and 14	US- PGPUB
15	BRS	L16	28	9 and 14 and 11	US- PGPUB